

# MEMORY

## CMOS

# 2 M × 8 BIT

# FAST PAGE MODE DYNAMIC RAM

## MB8117800B-50/-60

### CMOS 2,097,152 × 8 Bit Fast Page Mode Dynamic RAM

#### ■ DESCRIPTION

The Fujitsu MB8117800B is a fully decoded CMOS Dynamic RAM (DRAM) that contains 16,777,216 memory cells accessible in 8-bit increments. The MB8117800B features a “fast page” mode of operation whereby high-speed random access of up to 1,024 × 8 bits of data within the same row can be selected. The MB8117800B DRAM is ideally suited for mainframe, buffers, hand-held computers video imaging equipment, and other memory applications where very low power dissipation and high bandwidth are basic requirements of the design. Since the standby current of the MB8117800B is very small, the device can be used as a non-volatile memory in equipment that uses batteries for primary and/or auxiliary power.

The MB8117800B is fabricated using silicon gate CMOS and Fujitsu’s advanced four-layer polysilicon and two-layer aluminum process. This process, coupled with advanced stacked capacitor memory cells, reduces the possibility of soft errors and extends the time interval between memory refreshes. Clock timing requirements for the MB8117800B are not critical and all inputs are TTL compatible.

#### ■ PRODUCT LINE & FEATURES

Parameter		MB8117800B-50	MB8117800B-60
RAS Access Time		50 ns max.	60 ns max.
Random Cycle Time		90 ns min.	110 ns min.
Address Access Time		25 ns max.	30 ns max.
CAS Access Time		13 ns max.	15 ns max.
Fast Page Mode Cycle Time		35 ns min.	40 ns min.
Low Power Dissipation	Operating Current	715 mW max.	605 mW max.
	Standby Current	11 mW max. (TTL level)/5.5 mW max. (CMOS level)	

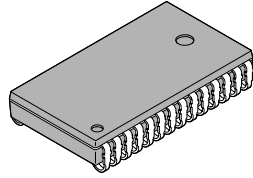
- 2,097,152 words × 8 bits organization
- Silicon gate, CMOS, Advanced Capacitor Cell
- All input and output are TTL compatible
- 2048 refresh cycles every 32.8 ms

- Early write or  $\overline{OE}$  controlled write capability
- RAS only, CAS-before-RAS, or Hidden Refresh
- Fast page mode, Read-Modify-Write capability
- On chip substrate bias generator for high performance

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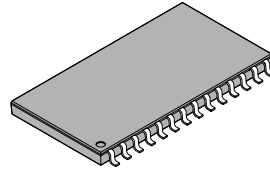
## ■ PACKAGE

28-pin plastic SOJ



(LCC-28P-M07)

28-pin plastic TSOP (II)



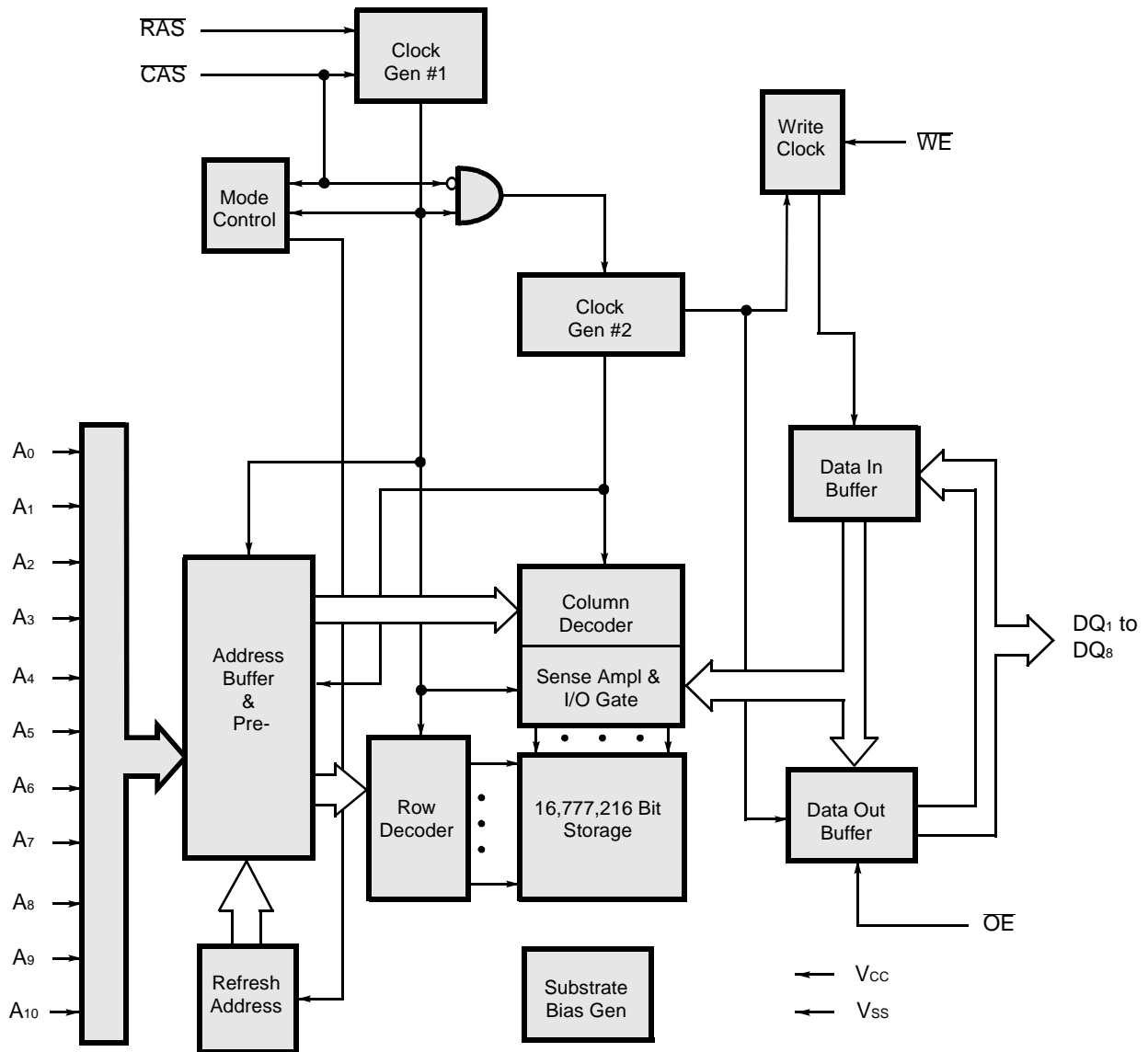
(FPT-28P-M14)  
(Normal Bend)

### Package and Ordering Information

- 28-pin plastic (400 mil) SOJ, order as MB8117800B-xxPJ
- 28-pin plastic (400 mil) TSOP-II with normal bend leads, order as MB8117800B-xxPFTN

# MB8117800B-50/-60

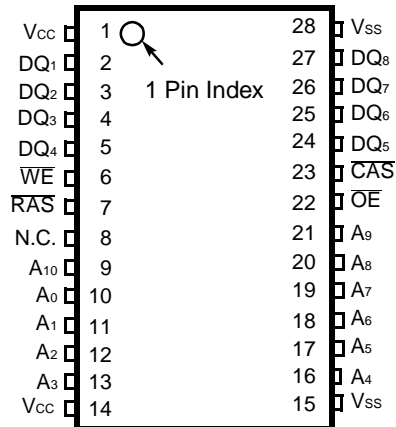
Fig. 1 - MB8117800B DYNAMIC RAM - BLOCK DIAGRAM



# MB8117800B-50/-60

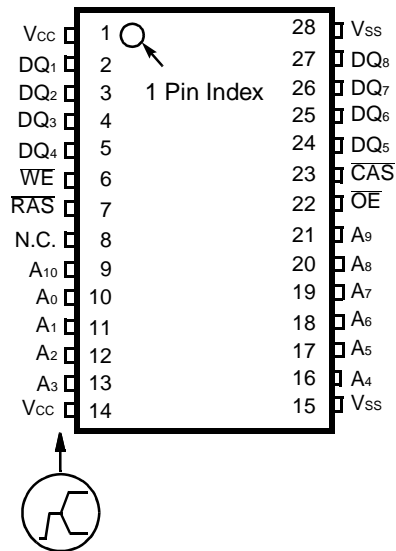
## ■ PIN ASSIGNMENTS AND DESCRIPTIONS

**28-Pin SOJ**  
(TOP VIEW)  
<LCC-28P-M07>



Designator	Function
A <sub>0</sub> to A <sub>10</sub>	Address inputs row : A <sub>0</sub> to A <sub>10</sub> column : A <sub>0</sub> to A <sub>9</sub> refresh : A <sub>0</sub> to A <sub>10</sub>
$\overline{\text{RAS}}$	Row address strobe
$\overline{\text{CAS}}$	Column address strobe
$\overline{\text{WE}}$	Write enable
$\overline{\text{OE}}$	Output enable
DQ <sub>1</sub> to DQ <sub>8</sub>	Data Input/Output
V <sub>CC</sub>	+5.0 volt power supply
V <sub>SS</sub>	Circuit ground

**28-Pin TSOP (II)**  
(TOP VIEW)  
<Normal Bend: LCC-28P-M14>



## FUNCTIONAL TRUTH TABLE

Operation Mode	Clock Input				Address Input		Input Data		Refresh	Note
	RAS	CAS	WE	OE	Row	Column	Input	Output		
Standby	H	H	X	X	—	—	—	High-Z	—	
Read Cycle	L	L	H	L	Valid	Valid	—	Valid	Yes*	$t_{RCS} \geq t_{RCS}(\text{min})$
Write Cycle (Early Write)	L	L	L	X	Valid	Valid	Valid	High-Z	Yes*	$t_{WCS} \geq t_{WCS}(\text{min})$
Read-Modify- Write Cycle	L	L	H→L	L→H	Valid	Valid	Valid	Valid	Yes*	
RAS-only Refresh Cycle	L	H	X	X	Valid	X	—	High-Z	Yes	
CAS-before-RAS Refresh Cycle	L	L	H	X	X	X	—	High-Z	Yes	$t_{CSR} \geq t_{CSR}(\text{min})$
Hidden Refresh Cycle	H→L	L	H→X	L	X	X	—	Valid	Yes	Previous data is kept.

X : "H" or "L"

\* : It is impossible in Fast Page Mode.

## FUNCTIONAL OPERATION

### ADDRESS INPUTS

Twenty-one input bits are required to decode any eight of 16,777,216 cell addresses in the memory matrix. Since only eleven address bits ( $A_0$  to  $A_{10}$ ) are available, the row and column inputs are separately strobed by  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$  as shown in Figure 1. First, eleven row address bits are input on pins  $A_0$ -through- $A_{10}$  and latched with the row address strobe ( $\overline{\text{RAS}}$ ) then, ten column address bits are input and latched with the column address strobe ( $\overline{\text{CAS}}$ ). Both row and column addresses must be stable on or before the falling edge of  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$ , respectively. The address latches are of the flow-through type; thus, address information appearing after  $t_{\text{RAH}}(\text{min}) + t_{\text{r}}$  is automatically treated as the column address.

### WRITE ENABLE

The read or write mode is determined by the logic state of  $\overline{\text{WE}}$ . When  $\overline{\text{WE}}$  is active Low, a write cycle is initiated; when  $\overline{\text{WE}}$  is High, a read cycle is selected. During the read mode, input data is ignored.

### DATA INPUTS

Input data is written into memory in either of three basic ways—an early write cycle, an  $\overline{\text{OE}}$  (delayed) write cycle, and a read-modify-write cycle. The falling edge of  $\overline{\text{WE}}$  or  $\overline{\text{CAS}}$ , whichever is later, serves as the input data-latch strobe. In an early write cycle, the input data ( $DQ_1$  to  $DQ_8$ ) is strobed by  $\overline{\text{CAS}}$  and the setup/hold times are referenced to  $\overline{\text{CAS}}$  because  $\overline{\text{WE}}$  goes Low before  $\overline{\text{CAS}}$ . In a delayed write or a read-modify-write cycle,  $\overline{\text{WE}}$  goes Low after  $\overline{\text{CAS}}$ ; thus, input data is strobed by  $\overline{\text{WE}}$  and all setup/hold times are referenced to the write-enable signal.

### DATA OUTPUTS

The three-state buffers are TTL compatible with a fanout of two TTL loads. Polarity of the output data is identical to that of the input; the output buffers remain in the high-impedance state until the column address strobe goes Low. When a read or read-modify-write cycle is executed, valid outputs are obtained under the following conditions:

- $t_{\text{RAC}}$  : from the falling edge of  $\overline{\text{RAS}}$  when  $t_{\text{RCD}}(\text{max})$  is satisfied.
- $t_{\text{CAC}}$  : from the falling edge of  $\overline{\text{CAS}}$  when  $t_{\text{RCD}}$  is greater than  $t_{\text{RCD}}(\text{max})$ .
- $t_{\text{AA}}$  : from column address input when  $t_{\text{RAD}}$  is greater than  $t_{\text{RAD}}(\text{max})$ .
- $t_{\text{OEA}}$  : from the falling edge of  $\overline{\text{OE}}$  when  $\overline{\text{OE}}$  is brought Low after  $t_{\text{RAC}}$ ,  $t_{\text{CAC}}$ , or  $t_{\text{AA}}$ .

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The data remains valid until either  $\overline{\text{CAS}}$  or  $\overline{\text{OE}}$  returns to a High logic level. When an early write is executed, the output buffers remain in a high-impedance state during the entire cycle.

## **FAST PAGE MODE OF OPERATION**

The fast page mode of operation provides faster memory access and lower power dissipation. The fast page mode is implemented by keeping the same row address and strobing in successive column addresses. To satisfy these conditions,  $\overline{\text{RAS}}$  is held Low for all contiguous memory cycles in which row addresses are common. For each fast page of memory, any of  $1,024 \times 8$  bits can be accessed and, when multiple MB8117800Bs are used,  $\overline{\text{CAS}}$  is decoded to select the desired memory fast page. Fast page mode operations need not be addressed sequentially and combinations of read, write, and/or read-modify-write cycles are permitted.

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## ■ ABSOLUTE MAXIMUM RATINGS (See WARNING)

Parameter	Symbol	Value	Unit
Voltage at Any Pin Relative to $V_{SS}$	$V_{IN}, V_{OUT}$	-0.5 to +7	V
Voltage of $V_{CC}$ Supply Relative to $V_{SS}$	$V_{CC}$	-0.5 to +7	V
Power Dissipation	$P_D$	1.0	W
Short Circuit Output Current	—	-50 to +50	mA
Operating Temperature	$T_{OPE}$	0 to 70	°C
Storage Temperature	$T_{STG}$	-55 to +125	°C

**WARNING:** Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

## ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Notes	Symbol	Min.	Typ.	Max.	Unit	Ambient Operating Temp.
Supply Voltage	*1	$V_{CC}$	4.5	5.0	5.5	V	0°C to +70°C
		$V_{SS}$	0	0	0		
Input High Voltage, All Inputs	*1	$V_{IH}$	2.4	—	6.5	V	
Input Low Voltage, All Inputs/Outputs*	*1	$V_{IL}$	-0.3	—	0.8	V	

\* : Undershoots of up to -2.0 volts with a pulse width not exceeding 20 ns are acceptable.

**WARNING:** Recommended operating conditions are normal operating ranges for the semiconductor device. All the device's electrical characteristics are warranted when operated within these ranges.

Always use semiconductor devices within the recommended operating conditions. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representative beforehand.

## ■ CAPACITANCE

( $T_A = 25^\circ\text{C}$ ,  $f = 1\text{ MHz}$ )

Parameter	Symbol	Typ.	Max.	Unit
Input Capacitance, $A_0$ to $A_{10}$	$C_{IN1}$	—	5	pF
Input Capacitance, $\overline{RAS}$ , $\overline{CAS}$ , $\overline{WE}$ , $\overline{OE}$	$C_{IN2}$	—	5	pF
Input/Output Capacitance, $DQ_1$ to $DQ_4$	$C_{DQ}$	—	7	pF

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## ■ DC CHARACTERISTICS

(At recommended operating conditions unless otherwise noted.)

Note 3

Parameter	Notes	Symbol	Conditions	Values			Unit
				Min.	Typ.	Max.	
Output High Voltage		$V_{OH}$	$I_{OH} = -5.0 \text{ mA}$	2.4	—	—	V
Output Low Voltage		$V_{OL}$	$I_{OL} = 4.2 \text{ mA}$	—	—	0.4	
Input Leakage Current (Any Input)		$I_{I(L)}$	$0 \text{ V} \leq V_{IN} \leq V_{CC}$ ; $4.5 \text{ V} \leq V_{CC} \leq 5.5 \text{ V}$ ; $V_{SS} = 0 \text{ V}$ ; All other pins under test = 0 V	-10	—	10	$\mu\text{A}$
Output Leakage Current		$I_{O(L)}$	$0 \text{ V} \leq V_{OUT} \leq V_{CC}$ ; $4.5 \text{ V} \leq V_{CC} \leq 5.5 \text{ V}$ ; Data out disabled	-10	—	10	
Operating Current (Average Power Supply Current)	*2	MB8117800B-50	$\overline{\text{RAS}}$ & $\overline{\text{CAS}}$ cycling; $t_{RC} = \text{min}$	—	—	130	mA
		MB8117800B-60				110	
Standby Current (Power Supply Current)	*2	TTL level	$\overline{\text{RAS}} = \overline{\text{CAS}} = V_{IH}$	—	—	2.0	mA
		CMOS level	$\overline{\text{RAS}} = \overline{\text{CAS}} \geq V_{CC} - 0.2 \text{ V}$			1.0	
Refresh Current #1 (Average Power Supply Current)	*2	MB8117800B-50	$\overline{\text{CAS}} = V_{IH}$ , $\overline{\text{RAS}}$ cycling; $t_{RC} = \text{min}$	—	—	130	mA
		MB8117800B-60				110	
Fast Page Mode Current	*2	MB8117800B-50	$\overline{\text{RAS}} = V_{IL}$ , $\overline{\text{CAS}}$ cycling; $t_{RC} = \text{min}$	—	—	100	mA
		MB8117800B-60				90	
Refresh Current #2 (Average Power Supply Current)	*2	MB8117800B-50	$\overline{\text{RAS}}$ cycling; $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ ; $t_{RC} = \text{min}$	—	—	130	mA
		MB8117800B-60				110	



## MB8117800B-50/-60

## ■ AC CHARACTERISTICS

(At recommended operating conditions unless otherwise noted.)

Notes 3, 4, 5

No.	Parameter	Notes	Symbol	MB8117800B-50		MB8117800B-60		Unit
				Min.	Max.	Min.	Max.	
1	Time between Refresh		t <sub>REF</sub>	—	32.8	—	32.8	ms
2	Random Read/Write Cycle Time		t <sub>RC</sub>	90	—	110	—	ns
3	Read-Modify-Write Cycle Time		t <sub>RWC</sub>	126	—	150	—	ns
4	Access Time from $\overline{\text{RAS}}$	*6,9	t <sub>RAC</sub>	—	50	—	60	ns
5	Access Time from $\overline{\text{CAS}}$	*7,9	t <sub>CAC</sub>	—	13	—	15	ns
6	Column Address Access Time	*8,9	t <sub>AA</sub>	—	25	—	30	ns
7	Output Hold Time		t <sub>OH</sub>	3	—	3	—	ns
8	Output Buffer Turn On Delay Time		t <sub>ON</sub>	0	—	0	—	ns
9	Output Buffer Turn Off Delay Time	*10	t <sub>OFF</sub>	—	13	—	15	ns
10	Transition Time		t <sub>T</sub>	3	50	3	50	ns
11	$\overline{\text{RAS}}$ Precharge Time		t <sub>RP</sub>	30	—	40	—	ns
12	$\overline{\text{RAS}}$ Pulse Width		t <sub>RAS</sub>	50	100000	60	100000	ns
13	$\overline{\text{RAS}}$ Hold Time		t <sub>RSH</sub>	13	—	15	—	ns
14	$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ Precharge Time		t <sub>CRP</sub>	5	—	5	—	ns
15	$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ Delay Time	*11,12	t <sub>RCD</sub>	17	37	20	45	ns
16	$\overline{\text{CAS}}$ Pulse Width		t <sub>CAS</sub>	13	—	15	—	ns
17	$\overline{\text{CAS}}$ Hold Time		t <sub>CSH</sub>	50	—	60	—	ns
18	$\overline{\text{CAS}}$ Precharge Time (Normal)	*19	t <sub>CPN</sub>	7	—	10	—	ns
19	Row Address Setup Time		t <sub>ASR</sub>	0	—	0	—	ns
20	Row Address Hold Time		t <sub>RAH</sub>	7	—	10	—	ns
21	Column Address Setup Time		t <sub>ASC</sub>	0	—	0	—	ns
22	Column Address Hold Time		t <sub>CAH</sub>	7	—	10	—	ns
23	Column Address Hold Time from $\overline{\text{RAS}}$		t <sub>AR</sub>	24	—	30	—	ns
24	$\overline{\text{RAS}}$ to Column Address Delay Time	*13	t <sub>RAD</sub>	12	25	15	30	ns
25	Column Address to $\overline{\text{RAS}}$ Lead Time		t <sub>RAL</sub>	25	—	30	—	ns
26	Column Address to $\overline{\text{CAS}}$ Lead Time		t <sub>CAL</sub>	25	—	30	—	ns
27	Read Command and Setup Time		t <sub>RCS</sub>	0	—	0	—	ns
28	Read Command Hold Time Referenced to $\overline{\text{RAS}}$	*14	t <sub>RRH</sub>	0	—	0	—	ns
29	Read Command Hold Time Referenced to $\overline{\text{CAS}}$	*14	t <sub>RCH</sub>	0	—	0	—	ns
30	Write Command Setup Time	*15	t <sub>WCS</sub>	0	—	0	—	ns
31	Write Command Hold Time		t <sub>WCH</sub>	7	—	10	—	ns
32	Write Command Hold Time from $\overline{\text{RAS}}$		t <sub>WCR</sub>	24	—	30	—	ns

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# MB8117800B-50/-60

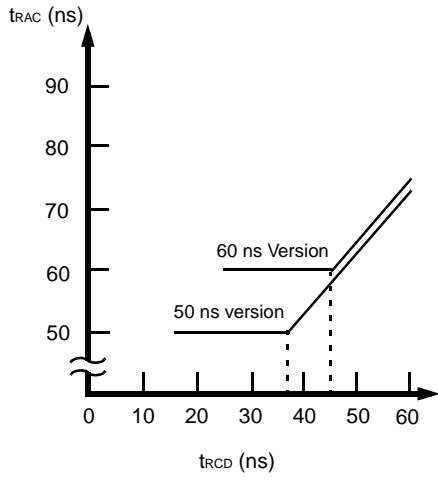
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No.	Parameter	Notes	Symbol	MB8117800B-50		MB8117800B-60		Unit
				Min.	Max.	Min.	Max.	
33	$\overline{WE}$ Pulse Width		t <sub>WP</sub>	7	—	10	—	ns
34	Write Command to $\overline{RAS}$ Lead Time		t <sub>RWL</sub>	13	—	15	—	ns
35	Write Command to $\overline{CAS}$ Lead Time		t <sub>CWL</sub>	13	—	15	—	ns
36	DIN Setup Time		t <sub>DS</sub>	0	—	0	—	ns
37	DIN Hold Time		t <sub>DH</sub>	7	—	10	—	ns
38	Data Hold Time from $\overline{RAS}$		t <sub>DHR</sub>	24	—	30	—	ns
39	$\overline{RAS}$ to $\overline{WE}$ Delay Time	*20	t <sub>RWD</sub>	68	—	80	—	ns
40	$\overline{CAS}$ to $\overline{WE}$ Delay Time	*20	t <sub>CWD</sub>	31	—	35	—	ns
41	Column Address to $\overline{WE}$ Delay Time	*20	t <sub>AWD</sub>	43	—	50	—	ns
42	$\overline{RAS}$ Precharge Time to $\overline{CAS}$ Active Time (Refresh cycles)		t <sub>RPC</sub>	5	—	5	—	ns
43	$\overline{CAS}$ Setup Time for $\overline{CAS}$ -before- $\overline{RAS}$ Refresh		t <sub>CSR</sub>	0	—	0	—	ns
44	$\overline{CAS}$ Hold Time for $\overline{CAS}$ -before- $\overline{RAS}$ Refresh		t <sub>CHR</sub>	10	—	10	—	ns
45	Access Time from $\overline{OE}$	*9	t <sub>OEA</sub>	—	13	—	15	ns
46	Output Buffer Turn Off Delay from $\overline{OE}$	*10	t <sub>OEZ</sub>	—	13	—	15	ns
47	$\overline{OE}$ to $\overline{RAS}$ Lead Time for Valid Data		t <sub>OEL</sub>	5	—	5	—	ns
48	$\overline{OE}$ Hold Time Referenced to $\overline{WE}$	*16	t <sub>OEH</sub>	5	—	5	—	ns
49	$\overline{OE}$ to Data In Delay Time		t <sub>OED</sub>	13	—	15	—	ns
50	$\overline{CAS}$ to Data In Delay Time		t <sub>CDD</sub>	13	—	15	—	ns
51	DIN to $\overline{CAS}$ Delay Time	*17	t <sub>DZC</sub>	0	—	0	—	ns
52	DIN to $\overline{OE}$ Delay Time	*17	t <sub>DZO</sub>	0	—	0	—	ns
60	Fast Page Mode $\overline{RAS}$ Pulse Width		t <sub>RASP</sub>	—	100000	—	100000	ns
61	Fast Page Mode Read/Write Cycle Time		t <sub>PC</sub>	35	—	40	—	ns
62	Fast Page Mode Read-Modify-Write Cycle Time		t <sub>PRWC</sub>	71	—	80	—	ns
63	Access Time from $\overline{CAS}$ Precharge	*9,18	t <sub>CPA</sub>	—	30	—	35	ns
64	Fast Page Mode $\overline{CAS}$ Precharge Time		t <sub>CP</sub>	7	—	10	—	ns
65	Fast Page Mode $\overline{RAS}$ Hold Time from $\overline{CAS}$ Precharge		t <sub>RHCP</sub>	30	—	35	—	ns
66	Fast Page Mode $\overline{CAS}$ Precharge to $\overline{WE}$ Delay Time	*20	t <sub>CPWD</sub>	48	—	55	—	ns

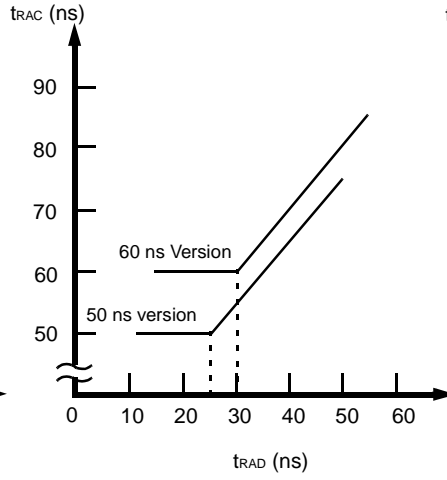
- Notes:**
- \*1. Referenced to  $V_{SS}$ .
  - \*2.  $I_{CC}$  depends on the output load conditions and cycle rates; the specified values are obtained with the output open.  $I_{CC}$  depends on the number of address change as  $\overline{RAS}=V_{IL}$ ,  $\overline{CAS}=V_{IH}$  and  $V_{IL} > -0.3$  V.  $I_{CC1}$ ,  $I_{CC3}$ ,  $I_{CC4}$  and  $I_{CC5}$  are specified at one time of address change during  $\overline{RAS}=V_{IL}$  and  $\overline{CAS}=V_{IH}$ .  $I_{CC2}$  is specified during  $\overline{RAS}=V_{IH}$  and  $V_{IL} > -0.3$  V.
  - \*3. An initial pause ( $\overline{RAS}=\overline{CAS}=V_{IH}$ ) of 200  $\mu$ s is required after power-up followed by any eight  $\overline{RAS}$ -only cycles before proper device operation is achieved. In case of using internal refresh counter, a minimum of eight  $\overline{CAS}$ -before- $\overline{RAS}$  initialization cycles instead of 8  $\overline{RAS}$  cycles are required.
  - \*4. AC characteristics assume  $t_T = 5$  ns.
  - \*5.  $V_{IH}$  (min) and  $V_{IL}$  (max) are reference levels for measuring timing of input signals. Also transition times are measured between  $V_{IH}$  (min) and  $V_{IL}$  (max).
  - \*6. Assumes that  $t_{RCD} \leq t_{RCD}(\max)$ ,  $t_{RAD} \leq t_{RAD}(\max)$ . If  $t_{RCD}$  is greater than the maximum recommended value shown in this table,  $t_{RAC}$  will be increased by the amount that  $t_{RCD}$  exceeds the value shown. Refer to Fig. 2 and 3.
  - \*7. If  $t_{RCD} \geq t_{RCD}(\max)$ ,  $t_{RAD} \geq t_{RAD}(\max)$ , and  $t_{ASC} \geq t_{AA} - t_{CAC} - t_T$ , access time is  $t_{CAC}$ .
  - \*8. If  $t_{RAD} \geq t_{RAD}(\max)$  and  $t_{ASC} \leq t_{AA} - t_{CAC} - t_T$ , access time is  $t_{AA}$ .
  - \*9. Measured with a load equivalent to two TTL loads and 100 pF.
  - \*10.  $t_{OFF}$  and  $t_{OEZ}$  is specified that output buffer change to high-impedance state.
  - \*11. Operation within the  $t_{RCD}(\max)$  limit ensures that  $t_{RAC}(\max)$  can be met.  $t_{RCD}(\max)$  is specified as a reference point only; if  $t_{RCD}$  is greater than the specified  $t_{RCD}(\max)$  limit, access time is controlled exclusively by  $t_{CAC}$  or  $t_{AA}$ .
  - \*12.  $t_{RCD}(\min) = t_{RAH}(\min) + 2 t_T + t_{ASC}(\min)$ .
  - \*13. Operation within the  $t_{RAD}(\max)$  limit ensures that  $t_{RAC}(\max)$  can be met.  $t_{RAD}(\max)$  is specified as a reference point only; if  $t_{RAD}$  is greater than the specified  $t_{RAD}(\max)$  limit, access time is controlled exclusively by  $t_{CAC}$  or  $t_{AA}$ .
  - \*14. Either  $t_{RRH}$  or  $t_{RCH}$  must be satisfied for a read cycle.
  - \*15.  $t_{WCS}$  is specified as a reference point only. If  $t_{WCS} \geq t_{WCS}(\min)$  the data output pin will remain High-Z state through entire cycle.
  - \*16. Assumes that  $t_{WCS} < t_{WCS}(\min)$ .
  - \*17. Either  $t_{DZC}$  or  $t_{DZO}$  must be satisfied.
  - \*18.  $t_{CPA}$  is access time from the selection of a new column address (that is caused by changing  $\overline{CAS}$  from "L" to "H"). Therefore, if  $t_{CP}$  is long,  $t_{CPA}$  is longer than  $t_{CPA}(\max)$ .
  - \*19. Assumes that  $\overline{CAS}$ -before- $\overline{RAS}$  refresh.
  - \*20.  $t_{WCS}$ ,  $t_{CWD}$ ,  $t_{RWD}$ ,  $t_{AWD}$ , and  $t_{CPWD}$  are not restrictive operating parameters. They are included in the data sheet as an electrical characteristic only. If  $t_{WCS} > t_{WCS}(\min)$ , the cycle is an early write cycle and DQ pin will maintain high-impedance state throughout the entire cycle. If  $t_{CWD} > t_{CWD}(\min)$ ,  $t_{RWD} > t_{RWD}(\min)$ , and  $t_{AWD} > t_{AWD}(\min)$ , the cycle is a read modify-write cycle and data from the selected cell will appear at the DQ pin. If neither of the above conditions is satisfied, the cycle is a delayed write cycle and invalid data will appear the DQ pin, and write operation can be executed by satisfying  $t_{RWL}$ ,  $t_{CWL}$ , and  $t_{RAL}$  specifications.

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**Fig. 2 – t<sub>RAC</sub> VS. t<sub>RCD</sub>**



**Fig. 3 – t<sub>RAC</sub> VS. t<sub>RAD</sub>**



**Fig. 4 – t<sub>CPA</sub> VS. t<sub>CP</sub>**

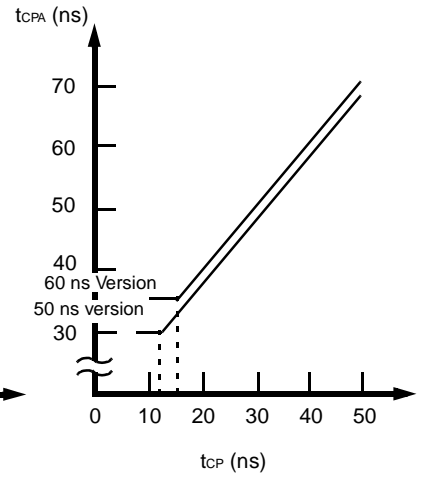
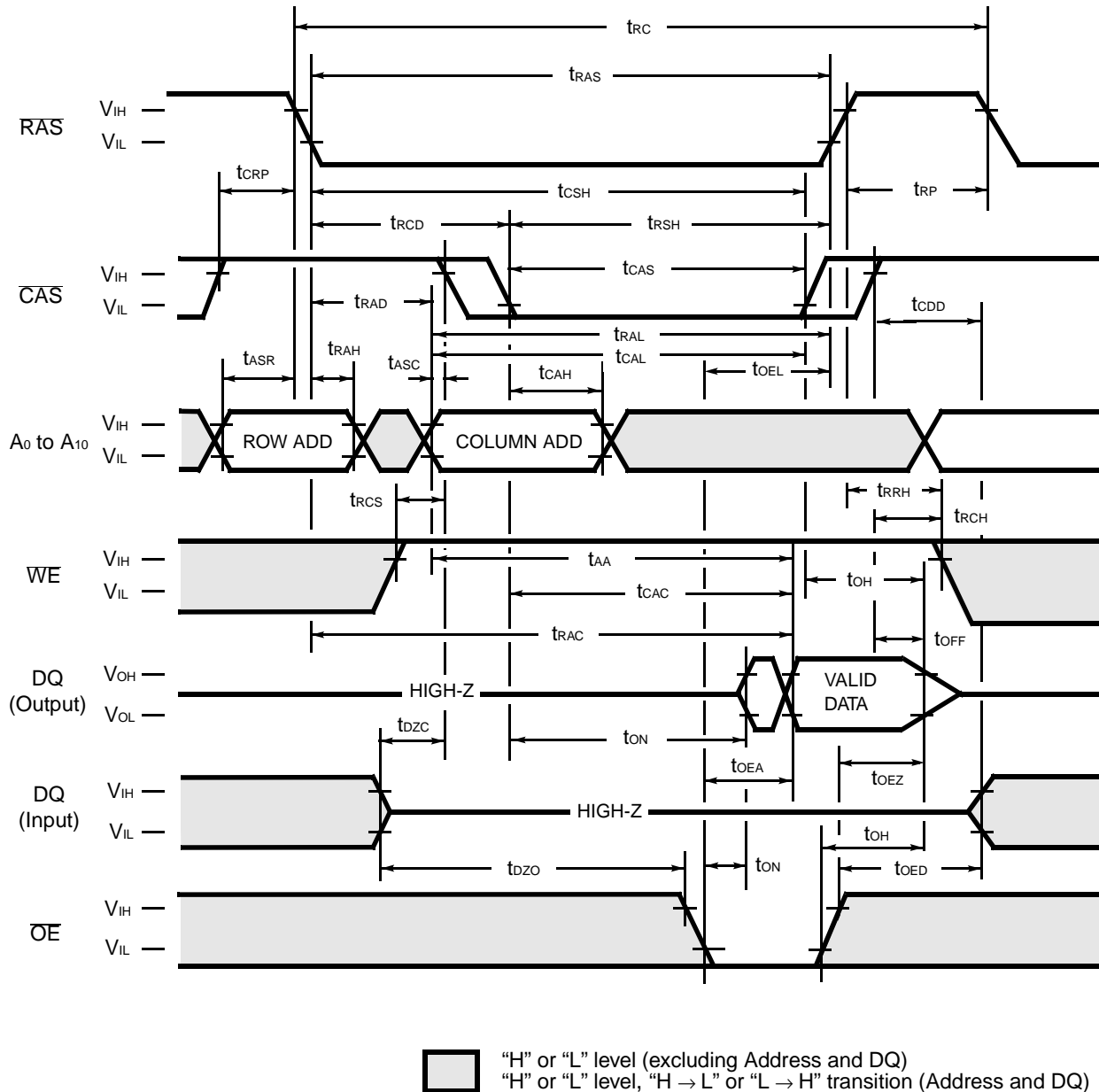


Fig. 5 – READ CYCLE

**DESCRIPTION**

To implement a read operation, a valid address is latched in by the  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$  address strobes and with  $\overline{\text{WE}}$  set to a High level and  $\overline{\text{OE}}$  set to a low level, the output is valid once the memory access time has elapsed. The access time is determined by  $\text{RAS}(t_{\text{RAC}})$ ,  $\text{CAS}(t_{\text{CAC}})$ ,  $\text{OE}(t_{\text{OEA}})$  or column addresses ( $t_{\text{AA}}$ ) under the following conditions:

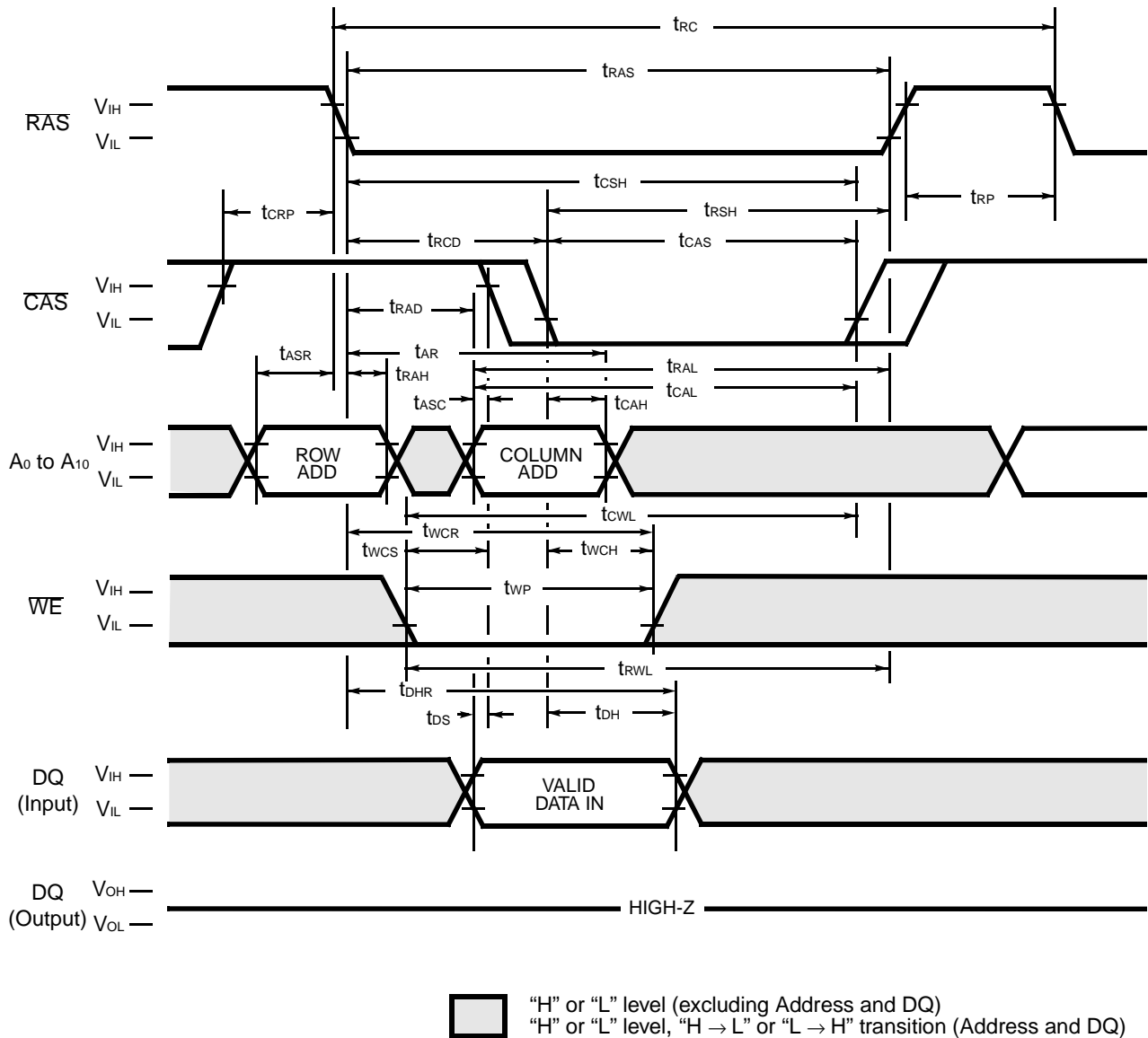
If  $t_{\text{RCD}} > t_{\text{RCD}}(\text{max})$ , access time =  $t_{\text{CAC}}$ .

If  $t_{\text{RAD}} > t_{\text{RAD}}(\text{max})$ , access time =  $t_{\text{AA}}$ .

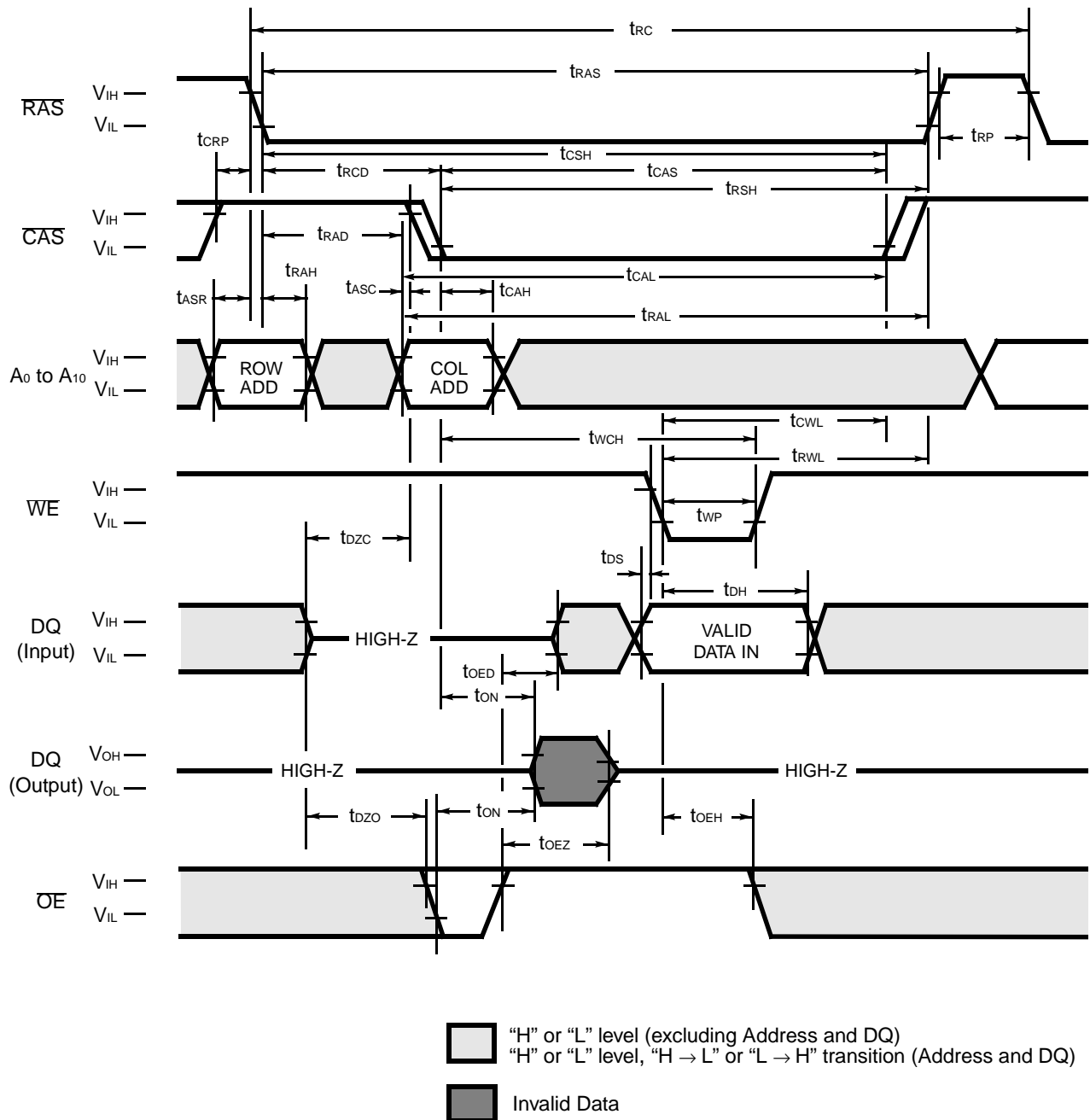
If  $\overline{\text{OE}}$  is brought Low after  $t_{\text{RAC}}$ ,  $t_{\text{CAC}}$ , or  $t_{\text{AA}}$  (whichever occurs later), access time =  $t_{\text{OEA}}$ .

However, if either  $\overline{\text{CAS}}$  or  $\overline{\text{OE}}$  goes High, the output returns to a high-impedance state after  $t_{\text{OH}}$  is satisfied.

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Fig. 6 – EARLY WRITE CYCLE ( $\overline{OE}$  = “H” or “L”)**DESCRIPTION**

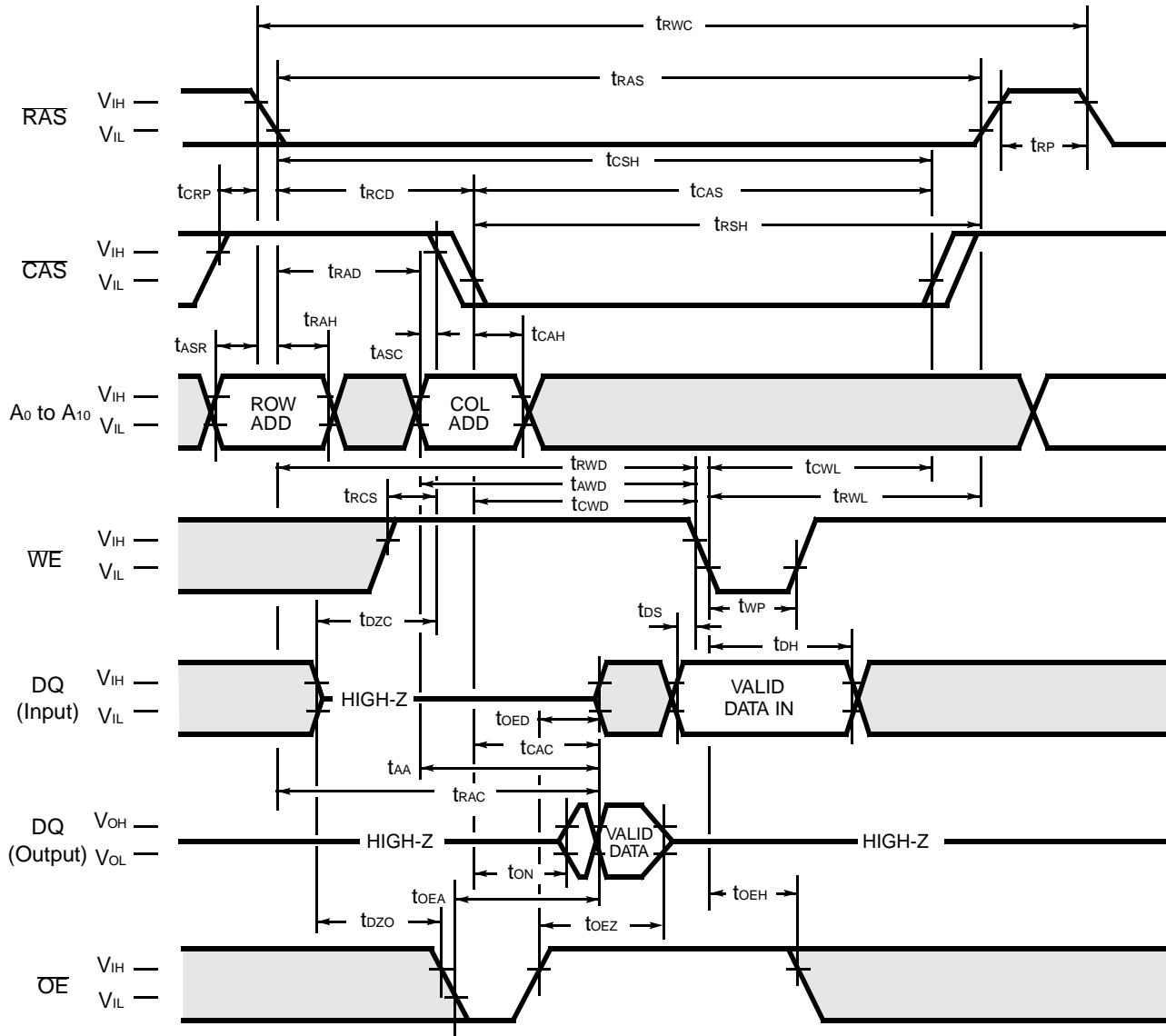
A write cycle is similar to a read cycle except  $\overline{WE}$  is set to a Low state and  $\overline{OE}$  is a "H" or "L" signal. A write cycle can be implemented in either of three ways—early write,  $\overline{OE}$  write (delayed write), or read-modify-write. During all write cycles, timing parameters  $t_{RWL}$ ,  $t_{CWL}$  and  $t_{RAL}$  must be satisfied. In the early write cycle shown above  $t_{WCS}$  satisfied, data on the DQ pin is latched with the falling edge of CAS and written into memory.



Fig. 7 - DELAYED WRITE CYCLE ( $\overline{OE}$  control)**DESCRIPTION**

In the  $\overline{OE}$  (delayed write) cycle,  $t_{wcs}$  is not satisfied; thus, the data on the DQ pins is latched with the falling edge of  $\overline{WE}$  and written into memory. The Output Enable ( $\overline{OE}$ ) signal must be changed from Low to High before  $\overline{WE}$  goes Low ( $t_{oED} + t_{ds}$ ).

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Fig. 8 – READ-MODIFY-WRITE-CYCLE



 "H" or "L" level (excluding Address and DQ)  
 "H" or "L" level, "H → L" or "L → H" transition (Address and DQ)

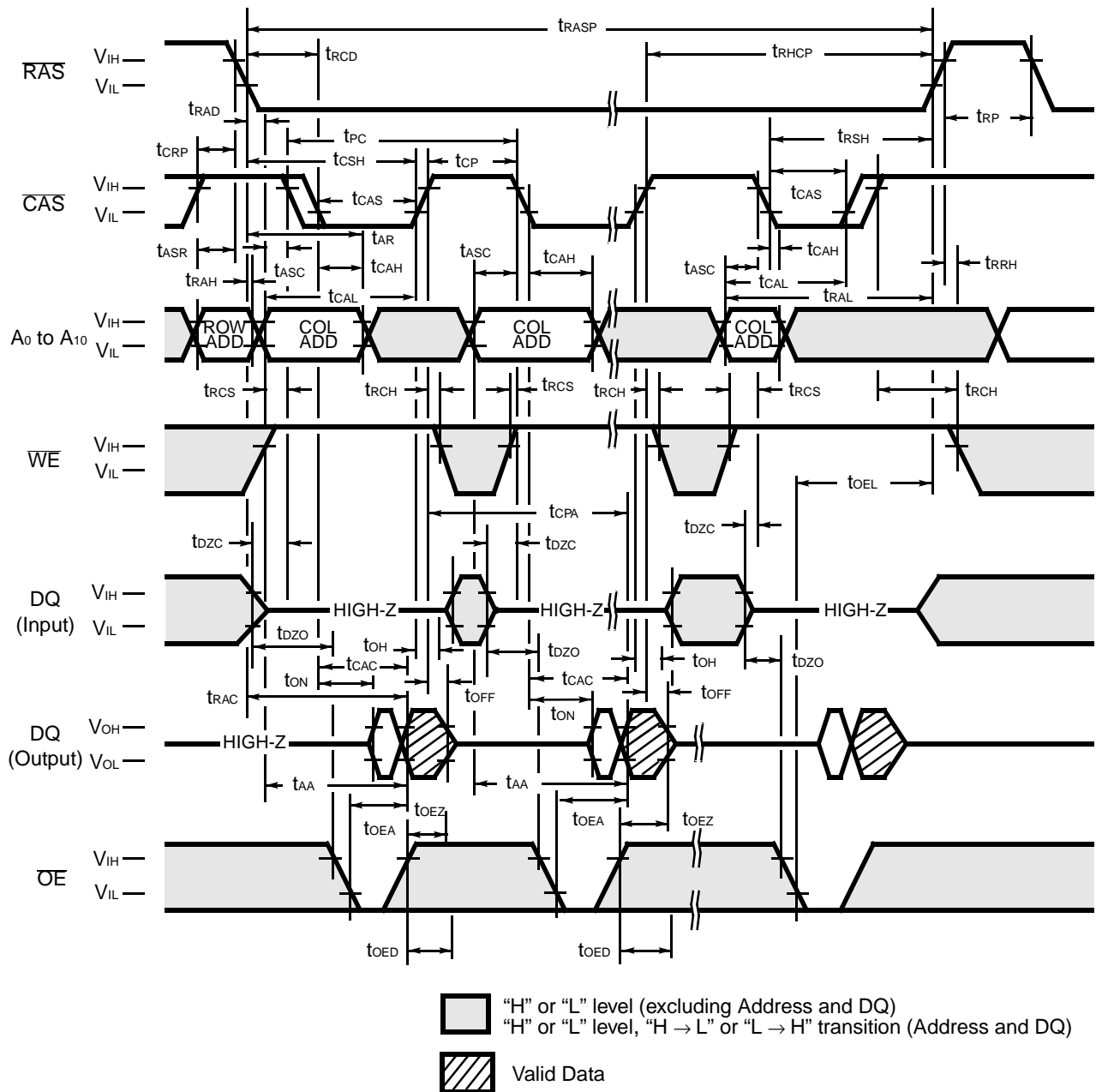
**DESCRIPTION**

The read-modify-write cycle is executed by changing  $\overline{WE}$  from High to Low after the data appears on the DQ pins. In the read-modify-write cycle,  $\overline{OE}$  must be changed from Low to High after the memory access time.



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Fig. 9 – FAST PAGE MODE READ CYCLE

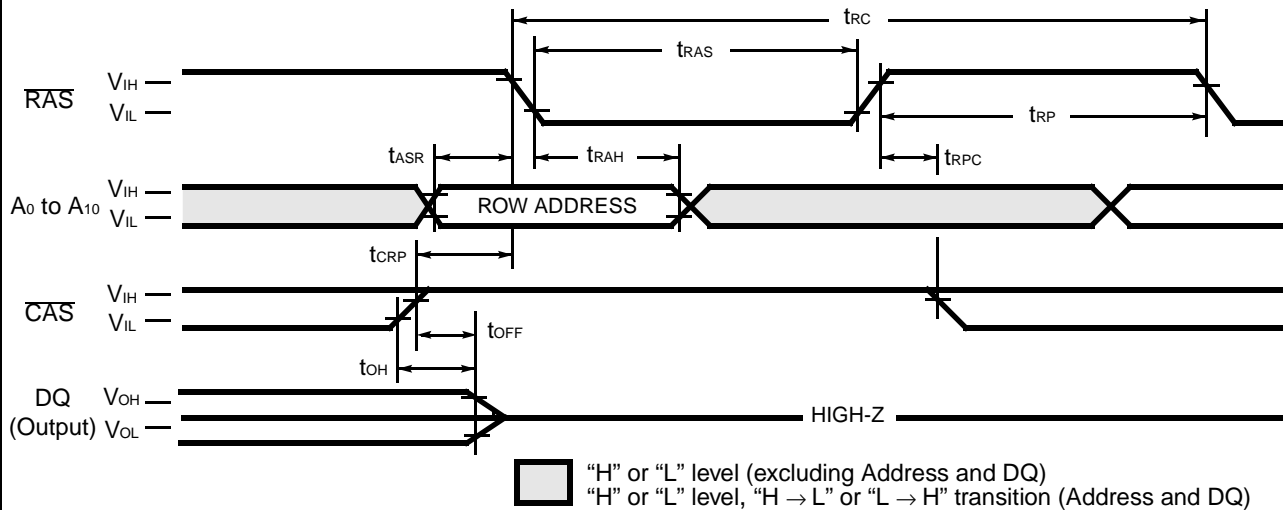
**DESCRIPTION**

The fast page mode of operation permits faster successive memory operations at multiple column locations of the same row address. This operation is performed by strobing in the row address and maintaining RAS at a Low level and WE at a High level during all successive memory cycles in which the row address is latched. The access time is determined by  $t_{CAC}$ ,  $t_{AA}$ ,  $t_{CPA}$ , or  $t_{OEA}$ , whichever one is the latest in occurring.



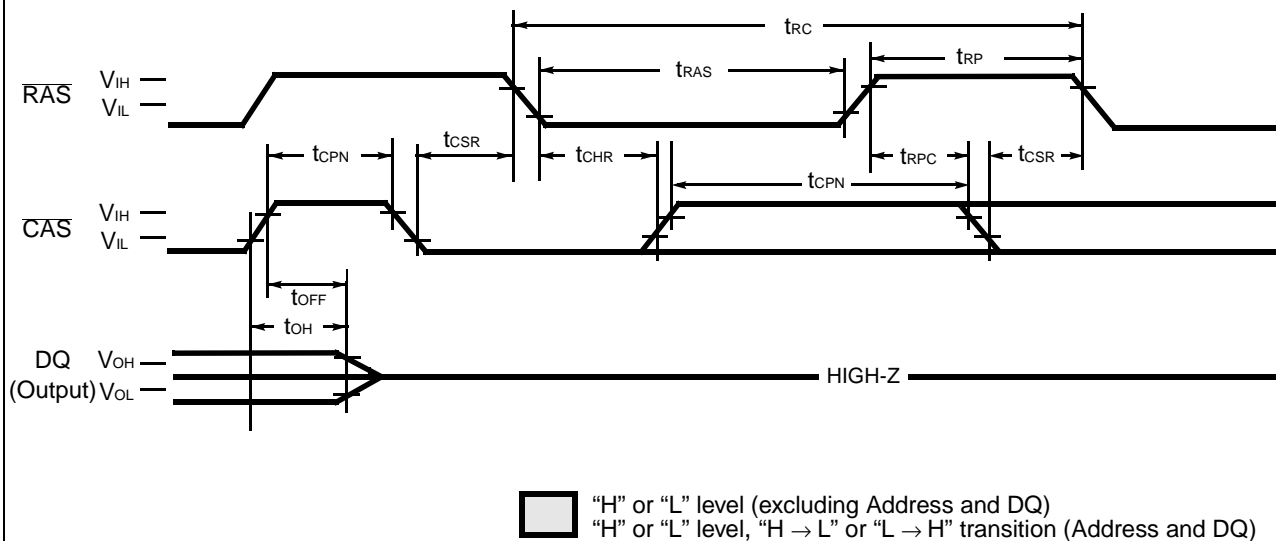




Fig. 13 - RAS-ONLY REFRESH ( $\overline{WE} = \overline{OE} = \text{"H" or "L"}$ )**DESCRIPTION**

Refresh of RAM memory cells is accomplished by performing a read, a write, or a read-modify-write cycle at each of 2048 row addresses every 32.8-milliseconds. Three refresh modes are available: RAS-only refresh, CAS-before-RAS refresh, and hidden refresh.

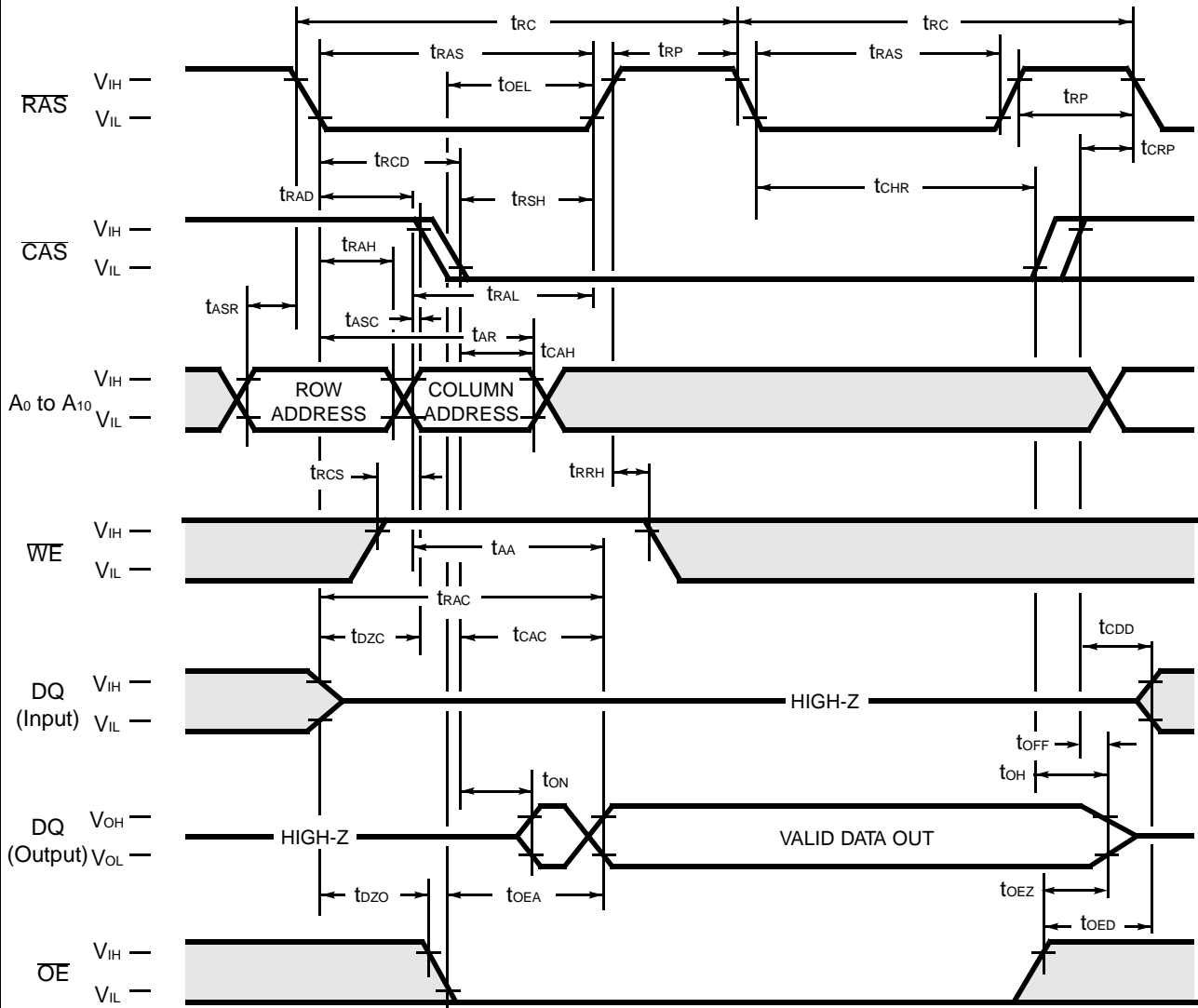
RAS-only refresh is performed by keeping RAS Low and CAS High throughout the cycle; the row address to be refreshed is latched on the falling edge of RAS. During RAS-only refresh, DQ pin is kept in a high-impedance state.


Fig. 14 - CAS-BEFORE-RAS REFRESH (ADDRESSES =  $\overline{OE} = \text{"H" or "L"}$ )**DESCRIPTION**

CAS-before-RAS refresh is an on-chip refresh capability that eliminates the need for external refresh addresses. If CAS is held Low for the specified setup time ( $t_{CSR}$ ) before RAS goes Low, the on-chip refresh control clock generators and refresh address counter are enabled. An internal refresh operation automatically occurs and the refresh address counter is internally incremented in preparation for the next CAS-before-RAS refresh operation.

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Fig. 15 – HIDDEN REFRESH CYCLE




 "H" or "L" level (excluding Address and DQ)  
 "H" or "L" level, "H → L" or "L → H" transition (Address and DQ)

**DESCRIPTION**

A hidden refresh cycle may be performed while maintaining the latest valid data at the output by extending the active time of  $\overline{\text{CAS}}$  and cycling RAS. The refresh row address is provided by the on-chip refresh address counter. This eliminates the need for the external row address that is required by DRAMs that do not have  $\overline{\text{CAS}}$ -before-RAS refresh capability.



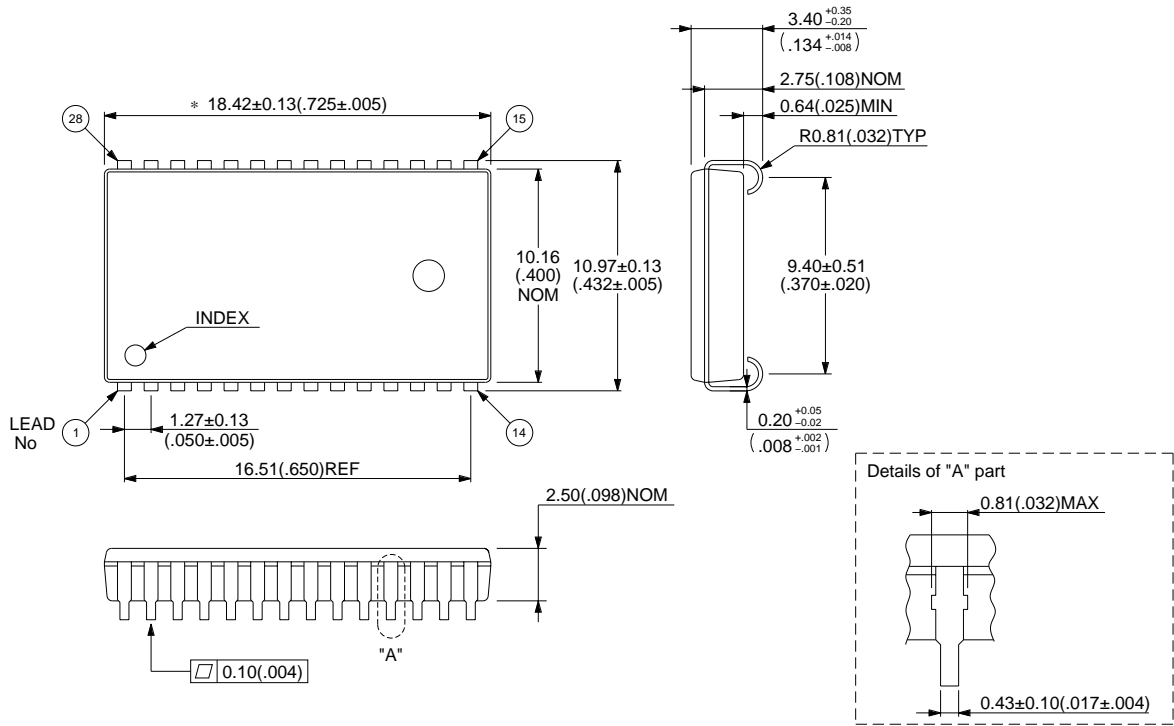
# MB8117800B-50/-60

## PACKAGE DIMENSIONS

(Suffix: -PJ)

28-pin plastic SOJ  
(LCC-28P-M07)

\* Resin protrusion. (Each side: 0.15(.006) max)



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Dimensions in mm (inches)



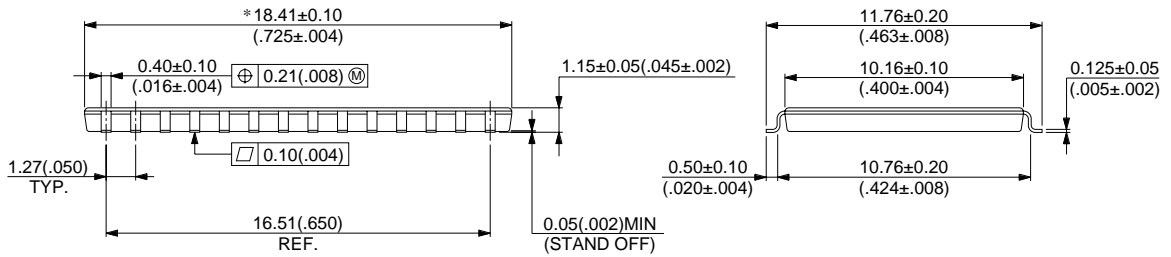
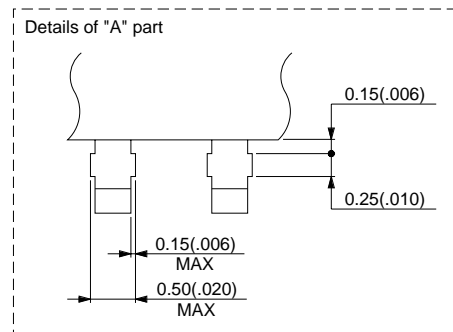
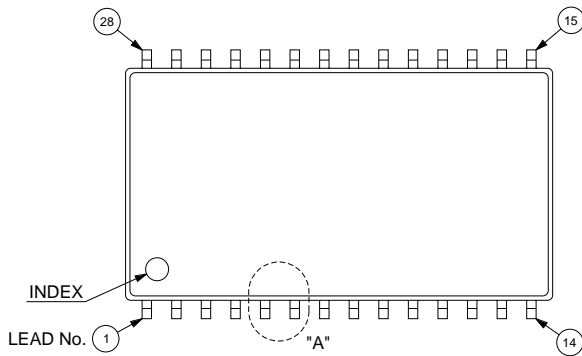
# MB8117800B-50/-60

(Continued)

(Suffix: -PFTN)

28-pin plastic TSOP (II)  
(FPT-28P-M14)

\* Resin protrusion. (Each side: 0.15(.006) max)



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Dimensions in mm (inches)

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